TÜV Rheinland Robotic Cell Compliance Roadmap

Critical Considerations for Robotic Cell Design

How does your cell stack up? Do you fully comply with the requirements of ANSI/RIA R15.06 Part 2, CSA Z434 Part 2 & EN ISO 10218-2?

Failure to consider these elements can cause severe safety risks, delays to market, product redesign, higher costs and long-term reputation damage.



RISK ASSESSMENT

- Was a risk assessment performed throughout the design and assembly of the robot cell?
- Does the risk assessment follow RIA TR R15.306, ANSI B11.0 or ISO 12100?
- Does the risk assessment take into consideration all the limits of the machinery?
- Does the risk assessment consider all hazards and all hazardous tasks?
- Was the risk estimated appropriately before safety measures were applied?
 - Was the hierarchy of risk reduction (Elimination, Substitution, Administrative Controls) followed?
- Was the risk re-evaluated after reduction measures were applied? Was the risk sufficiently low?
- □ If a safety related control system was used for risk reduction, was a performance level (PL) or safety integrity level (SIL) required? Was this requirement met?



EMERGENCY STOP FUNCTION

- Does each control station capable of initiating motion have a manually initiated emergency stop?
- Does the stop function comply with IEC 60204-1 and ISO 13850?



SAFETY-RELATED CONTROL SYSTEM PERFORMANCE (HARDWARE/SOFTWARE)

- Do all safety related control systems meet at least PLd CAT 3 or SIL 2? If lower, was this justified by a risk assessment?
 - Has an assessment of each safety interlock circuit been done in accordance with ISO 13849-1 and/or IEC 62061?



SAFEGUARDING

П	Do safety distances over and through mechanical
	guarding meet the requirements in ISO 13857?

Do the minimum distances from interlocking guards and other trip devices (laser scanners, light curtains, safety cameras, etc.) meet the requirements in ISO 13855?

□ Do fixed and moveable guards meet the requirements of ISO 14120? Do their minimum distances from any hazard meet the relevant requirements of ISO 13857?

Do the interlocking devices associated with moveable
guards meet the requirements of ISO 14119?



INFORMATION FOR USE

Does the information for use contain all of the following information?

- Handling
- Installation and commissioning
- Information for commissioning test or initial start-up procedure
- System information
- Use of the system
- Maintenance
- De-commissioning
- Emergency situations
- Robot specific information



VERIFICATION AND VALIDATION

Was a verification and validation of the design of the robot system performed to show compliance with ANSI/ RIA R15.06 Part 2, CAN/CSA Z434 Part 2 & EN/ISO 10218-2?

Is the document available in the information for use?



HAZARDOUS ENERGY

Has the robot cell been evaluated and either listed or labelled in accordance with NFPA 79 and/or IEC 60204-1?

Does the robot cell comply with ISO 4413 and ISO 4414 as applicable?



LIMITING ROBOT MOTION



- ☐ If the motion of the robot is limited by means integral to the robot (safety-rated soft axis and space limiting) is this safety rated and does it meet PLd CAT 3 or SIL 2? Are the programmed limits available in the information for use?
- ☐ If the perimeter guard is the limiting device, do the results of the risk assessment determine the requirements for the design, strength and deflection for that guard?



COLLABORATIVE ROBOT OPERATION

- Does the risk assessment consider all collaborative tasks and potential contact situations?
- Is one or more of the 4 safety features (safety-rated monitored stop, hand guiding, speed and separation monitoring, power and force limiting) utilized properly and validated?



Need additional information to create a compliance roadmap for your robotic cells? Contact TÜV Rheinland and our experts can help your team build a comprehensive compliance plan. TÜV Rheinland AG Am Grauen Stein 51105 Cologne, Germany Phone +49 221 806-0 www.tuv.com

